

# ARES: Predictable Traffic Engineering under Controller Failures in SD-WANs



Songshi Dou<sup>†‡§</sup>, Li Qi<sup>‡§</sup>, and Zehua Guo<sup>‡\*§</sup>

<sup>†</sup>The University of Hong Kong, <sup>‡</sup>Beijing Institute of Technology, <sup>§</sup>Zhejiang Lab,

<sup>\*</sup>Beijing Institute of Technology Zhengzhou Academy of Intelligent Technology



## ① Introduction

### • TE Meets Various QoS Requirements for Web Services through SD-WANs

- Cloud services bring new web applications:
  - web services, video streaming, web AR/VR ...
- Web services account for *a large share of* Wide Area Network (WAN) traffic.
- Traffic Engineering (TE) improves the network performance of WANs and *enables differentiable QoS* for web applications.
- SDN brings the *flexible management* of WANs since TE can be implemented at the SDN controller to update routing policies for accommodating potential traffic fluctuations.

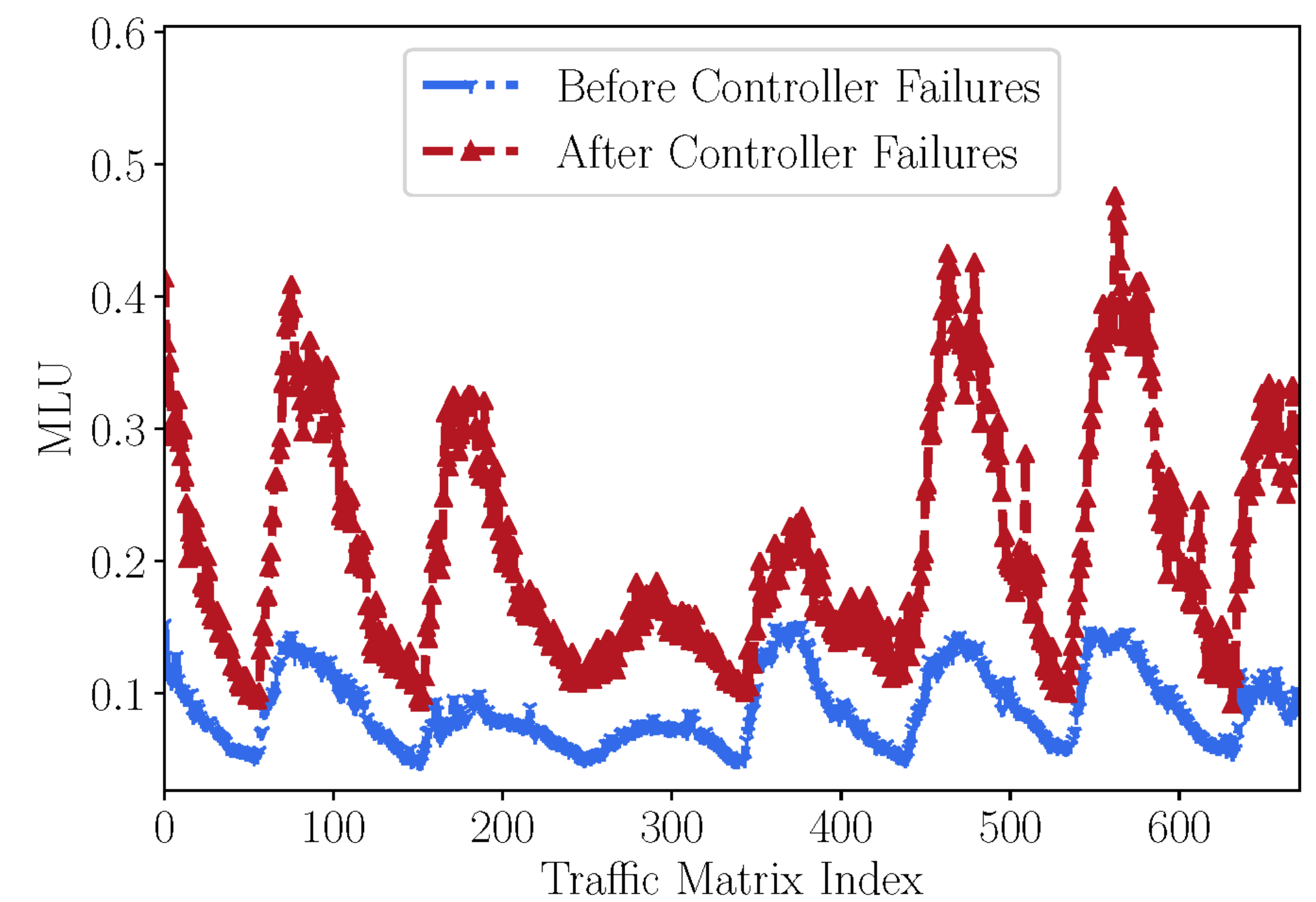
### • Controller Failures Pose Severe Impact on TE Performance

- Controller failure is *a common problem* in SD-WANs.
  - power outage, malicious attacks ...
- Switches previously controlled by the failed controller become *offline switches*, and flows traversing these offline switches *become offline and lose their path programmability*.
- Network performance cannot be guaranteed to accommodate potential traffic variations due to the *loss of flexible network management*, leading to *significant TE performance degradation* with a large number of offline flows.

### • State-of-the-Art Solutions and Their Limitations

- Reassign offline switches to other active controllers.
- Path programmability-centric* solutions.
- While higher path programmability implies *a higher likelihood of accommodating unpredictable future traffic fluctuations*, it *cannot guarantee a predictable TE performance*.

## ② Observation & Motivation

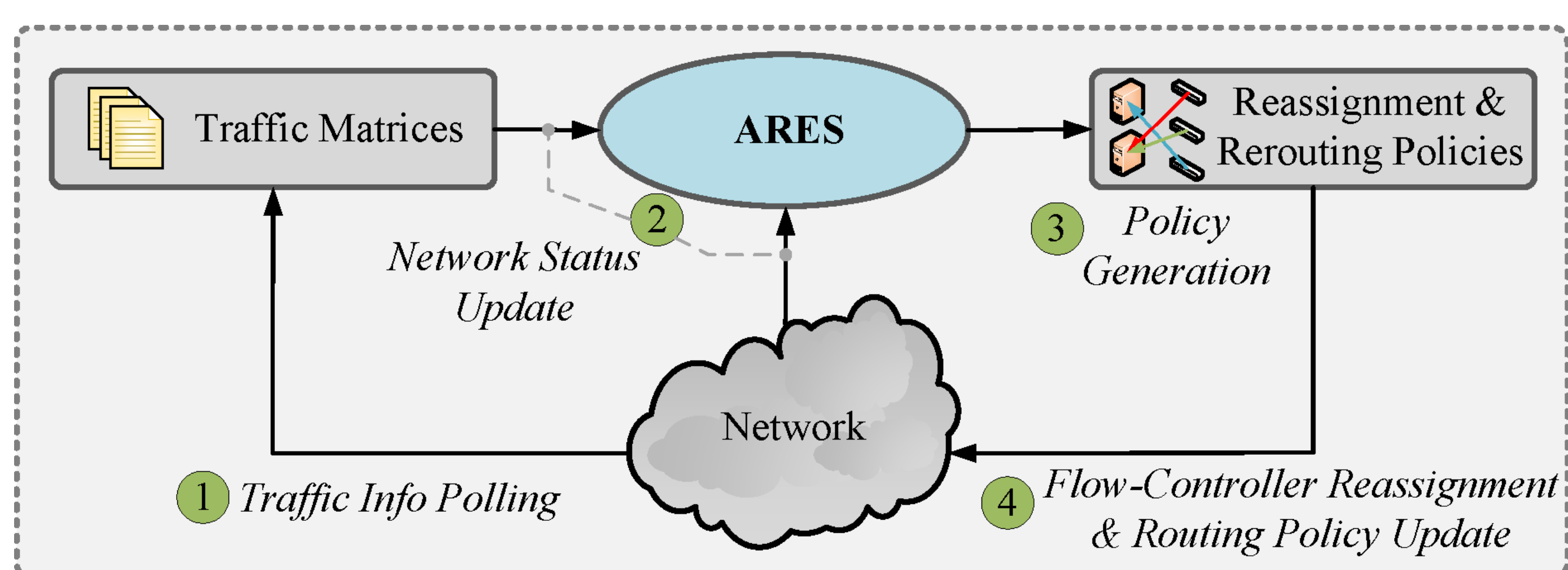


Comparison of the MLU performance before and after controller failures. The lower, the better.

### • Observation: impact of controller failures on TE performance

- Doing TE operations with the objective of *minimizing the Maximum Link Utilization (MLU)*.
- GEANT topology with real-world Traffic Matrices (TMs):
  - Topology: 23 switches, 72 links.
  - TMs: every 15 minutes, a total of 672 TMs during one week.
- Blue line:** the MLU performance *before* controller failures
- Red line:** the MLU performance *after* controller failures.
- This observation demonstrates that controller failures *threaten TE performance*, which can *increase the MLU by up to 0.35* in the worst case.
- The root cause lies in that *flows cannot be flexibly rerouted* to accommodate traffic fluctuations due to controller failures.

## ③ Solution - ARES



The processing logic of ARES.

### • Opportunity: fine-grained flow-controller reassignment

- P4 Runtime specification is designed for P4 programmable switches and *allows multiple controllers to manage the switch*.
- This feature *aligns with the design goal* of enabling multiple controllers to manage a single switch.

### • Overview of ARES

- Firstly, it collects *real-time traffic traces* (e.g., TMs) from the network periodically.
- Secondly, when controller failures occur, ARES *updates the current network status* with the required information (e.g., collected TMs, offline flows, and active controllers).
- Subsequently, *flow-controller reassignment and flow rerouting policies* are determined and generated by solving the proposed optimization problem / heuristic algorithm (detailed in the paper).
- Finally, ARES *reassigns offline flows* to corresponding active controllers and *updates routing policies*, achieving predictable load balancing performance in the whole network.

## ④ Evaluation Results

| Scheme             | One controller failure | Two controller failures |
|--------------------|------------------------|-------------------------|
| OSPF               | 44.46 +/- 0%           | 44.46 +/- 0%            |
| ECMP               | 56.78 +/- 0%           | 56.78 +/- 0%            |
| OPT-OSCM [23]◊     | 60.57 +/- 6.68%        | 55.68 +/- 6.97%         |
| OPT-FRSM [24]◊     | 58.09 +/- 4.18%        | 51.40 +/- 5.44%         |
| OPT-FMSSM [25]◊    | 58.50 +/- 4.44%        | 52.42 +/- 4.49%         |
| <b>OPT-TPFCRFR</b> | <b>100.00 +/- 0%</b>   | <b>100.00 +/- 0%</b>    |

Average PR Performance of proposed formulation and existing formulations.

| Scheme      | One controller failure | Two controller failures |
|-------------|------------------------|-------------------------|
| OSPF        | 44.46 +/- 0%           | 44.46 +/- 0%            |
| ECMP        | 56.78 +/- 0%           | 56.78 +/- 0%            |
| RetroFlow♠  | 64.01 +/- 0%           | 63.70 +/- 0.25%         |
| Matchmaker♠ | 57.46 +/- 4.05%        | 50.49 +/- 4.24%         |
| PM♠         | 60.97 +/- 2.85%        | 51.44 +/- 4.18%         |
| <b>ARES</b> | <b>87.82 +/- 1.69%</b> | <b>87.23 +/- 1.19%</b>  |

Average PR Performance of ARES and existing solutions.

### • Evaluation results

- GEANT Topology: 23 switches, 72 links.
- Real-world TMs: every 15 minutes, a total of 672 TMs.
- Performance Ratio (PR):**  $PR = P_{scheme} / P_{optimal}$ . A PR value of 1 implies that the scheme performs on par with the optimal results.
- Our problem formulation** exhibits comparable load balancing performance to optimal TE solution without controller failures, and **ARES** significantly improves average load balancing performance by up to 43.36% with low computation time, compared with baseline approaches.